# Math 304 Sample Final

Name:

### This exam has 11 questions, for a total of 150 points.

Please answer each question in the space provided. Please write **full solutions**, not just answers. Cross out anything the grader should ignore and circle or box the final answer.

Question	Points	Score
1	10	
2	15	
3	10	
4	10	
5	10	
6	20	
7	20	
8	15	
9	10	
10	15	
11	15	
Total:	150	

# Question 1. (10 pts)

Determine the following statements are true or false.

(a) If B is diagonalizable, then  $B^2$  is also diagonalizable.

Solution: True.

(b) If  $\vec{v}_1, \vec{v}_2, \dots, \vec{v}_n$  span  $\mathbb{R}^8$ , then *n* must be 8.

Solution: False.

(c) If  $\vec{v}_1, \vec{v}_2, \dots, \vec{v}_n$  are linear independent in  $\mathbb{R}^7$ , then *n* must be at most 7.

Solution: True.

(d) Suppose that A is a diagonalizable  $5 \times 5$  matrix. If  $A^5 = 0$ , then A must be the zero matrix.

Solution: True.

(e) Suppose  $\vec{v}_1$ ,  $\vec{v}_2$  and  $\vec{v}_3$  form a basis of  $\mathbb{R}^3$ , then  $\vec{v}_1$ ,  $(\vec{v}_1 + \vec{v}_2)$  and  $(\vec{v}_1 + \vec{v}_2 + \vec{v}_3)$  also form a basis of  $\mathbb{R}^3$ .

Solution: True.

#### Question 2. (15 pts)

(a) Let A be a  $(4 \times 4)$  matrix. We view A as a linear mapping  $\mathbb{R}^4 \to \mathbb{R}^4$ . Suppose  $\det(A) \neq 0$ . What is the dimension of the range of A? Justify your answer.

Solution: det  $A \neq 0$  implies that Ker  $A = \{0\}$ . We know that dim  $\mathbb{R}^4$  = dim Im A + dim Ker A. Therefore, dim Im A = 4 - 0 = 4

(b) Suppose  $F : \mathbb{R}^5 \to \mathbb{R}^3$  is linear mapping. Is it possible that dim ker F = 0? Justify your answer.

Solution: We have the following formula  $\dim R^5 = \dim \operatorname{Ker} F + \dim \operatorname{Im} F$ Note that dim Im F is a subspace of  $\mathbb{R}^3$ . In particular,  $\dim \operatorname{Im} F \leq 3.$ We also know that  $\dim R^5 = \dim \operatorname{Im} F + \dim \operatorname{Ker} F.$ 

This implies that dim Ker  $F = 5 - \dim \operatorname{Im} F \ge 2$ . So F cannot be injective.

(c) Let  $B : \mathbb{R}^2 \to \mathbb{R}^2$  be a linear mapping. What are the possible integer values that  $\dim(\ker B)$  can take? List all possibilities.

**Solution:** All possible values of  $\dim(\ker B)$  are 0, 1 and 2.

# Question 3. (10 pts)

Find the determinant of

$$\begin{bmatrix} 1 & 2 & 4 \\ 0 & 0 & 1 \\ 0 & 1 & 2 \end{bmatrix}$$

Solution: It is a standard computation. I skip the details. The determinant is -1.

# Question 4. (10 pts)

Find all eigenvalues and eigenvectors of the matrix

$$A = \begin{bmatrix} 4 & 2-i \\ 2+i & 0 \end{bmatrix}$$

# Solution:

$$\det(A - \lambda I) = \begin{vmatrix} 4 - \lambda & 2 - i \\ 2 + i & -\lambda \end{vmatrix} = -\lambda(4 - \lambda) - 5 = (\lambda - 5)(\lambda + 1)$$

When  $\lambda = 5$ , the eigenvector is

$$v = \begin{bmatrix} (2-i) \\ 1 \end{bmatrix}$$

When  $\lambda = -1$ , the eigenvector is

$$w = \begin{bmatrix} -1\\(2+i) \end{bmatrix}$$

Question 5. (10 pts)

Given the vectors

$$u_{1} = \begin{bmatrix} 1\\1\\1\\0 \end{bmatrix}, u_{2} = \begin{bmatrix} 1\\2\\3\\0 \end{bmatrix}, u_{3} = \begin{bmatrix} 1\\5\\8\\1 \end{bmatrix}$$

in  $\mathbb{R}^4$ . Determined whether  $v = (3, 0, 1, 4)^T$  is in the span of  $u_1, u_2, u_3$ .

Solution: Form the augmented matrix	
$\begin{bmatrix} 1 & 1 & 1 &   & 3 \\ 1 & 2 & 5 & 0 \\ 1 & 3 & 8 & 1 \\ 0 & 0 & 1 &   & 4 \end{bmatrix}$	
Its row echelon form is	

So the system is inconsistent. So v is not in the span of  $u_1, u_2, u_3$ .

# Question 6. (20 pts) Given the matrix

$$A = \begin{bmatrix} 1 & 0 & 2 & 4 \\ 0 & 1 & -3 & -1 \\ 3 & 4 & -6 & 8 \\ 0 & -1 & 3 & 1 \end{bmatrix}$$

(a) Find the reduced row echelon form of A.

Solution:	I skip the details.	The	rov	v e	chelo	n form	is
	· · · · · · · · · · · · · · · · · · ·	A =	$\begin{bmatrix} 1\\ 0\\ 0\\ 0 \end{bmatrix}$	$egin{array}{c} 0 \\ 1 \\ 0 \\ 0 \end{array}$	$\begin{array}{c}2\\-3\\0\\0\end{array}$	$\begin{bmatrix} 4\\ -1\\ 0\\ 0 \end{bmatrix}$	

(b) Find a basis for the kernel of A.

Solution: All elements in the kernel are of the form
$$s \begin{pmatrix} -4\\1\\0\\1 \end{pmatrix} + t \begin{pmatrix} -2\\3\\1\\0 \end{pmatrix}$$
So
$$v_1 = \begin{pmatrix} -4\\1\\0\\1 \end{pmatrix}, v_2 = \begin{pmatrix} -2\\3\\1\\0 \end{pmatrix}$$
form a basis of ker 4

form a basis of ker A.

(c) Find a basis for the range of A.

**Solution:** The first and second columns contain pivotal entries. So the corresponding columns in A form a basis of the range of A, that is,

$$\begin{pmatrix} 1\\0\\3\\0 \end{pmatrix}, \begin{pmatrix} 0\\1\\4\\-1 \end{pmatrix}$$

### Question 7. (20 pts)

Determine whether the matrix  $A = \begin{bmatrix} 1 & 1 & 1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$  is diagonalizable. If yes, find a nonsingular matrix S and a diagonal matrix D such that  $A = SDS^{-1}$ .

Solution: Use cofactor expansion along the first column  $\det(A - \lambda I) = \begin{vmatrix} 1 - \lambda & 1 & 1 \\ 0 & -\lambda & 0 \\ 0 & 0 & -\lambda \end{vmatrix} = (1 - \lambda)\lambda^2$ 

So  $\lambda = 1$  and 0.

When  $\lambda = 1$ , solve for the kernel of the matrix

$$\begin{bmatrix} 0 & 1 & 1 \\ 0 & -1 & 0 \\ 0 & 0 & -1 \end{bmatrix}$$

We find an eigenvector  $v = \begin{bmatrix} 1\\0\\0 \end{bmatrix}$ .

When  $\lambda = 0$ , solve for the kernel of the matrix

$$\begin{bmatrix} 1 & 1 & 1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

We find an eigenvector  $w_1 = \begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix}$  and  $w_2 = \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix}$ .

We can verify that v,  $w_1$  and  $w_2$  are linearly independent. It follows that A has 3 linearly independent eigenvectors, so A is diagonalizable. Let

$$S = \begin{bmatrix} 1 & -1 & -1 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \text{ and } D = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

Then  $A = SDS^{-1}$ .

# Question 8. (15 pts)

Let V be the subspace of  $\mathbb{R}^4$  spanned by

$$\vec{v}_1 = \begin{bmatrix} 0\\4\\0\\0 \end{bmatrix}, \quad \vec{v}_2 = \begin{bmatrix} 1\\3\\0\\1 \end{bmatrix}, \quad \vec{v}_3 = \begin{bmatrix} 4\\5\\8\\4 \end{bmatrix}.$$

(a) Use Gram-Schmidt process to find an orthonormal basis of V.

Solution: I skip the details.

$$u_1 = \frac{v_1}{\|v_1\|} = (0, 1, 0, 0)^T$$
$$u_2 = (\frac{1}{\sqrt{2}}, 0, 0, \frac{1}{\sqrt{2}})^T$$
$$u_3 = (0, 0, 1, 0)^T$$

(b) Find the projection of

$$\vec{x} = \begin{bmatrix} 3\\ -1\\ 5\\ 0 \end{bmatrix}$$

onto V.

Solution: The projection is  $\langle \vec{x}, u_1 \rangle u_1 + \langle \vec{x}, u_2 \rangle u_2 + \langle \vec{x}, u_3 \rangle u_3 = \begin{bmatrix} 3/2 \\ -1 \\ 5 \\ 3/2 \end{bmatrix}$ 

# Question 9. (10 pts)

Let  $\mathbb{P}_2 = \{ all \text{ polynomials of degree } \leq 2 \}$ . We define the following inner product on  $\mathbb{P}_2$ :

$$\langle p,q\rangle = \int_{-1}^1 p(x)q(x)dx.$$

Find the angle between x + 1 and  $x^2$ .

Solution:  

$$||x+1||^2 = \int_{-1}^{1} (x+1)^2 dx = \frac{8}{3}$$
  
So  $||x+1|| = \sqrt{\frac{8}{3}}$ . Similarly, we compute  $||x^2|| = \sqrt{\frac{2}{5}}$ .  
 $\langle x+1, x^2 \rangle = \frac{2}{3}$   
So  
 $\cos \theta = \frac{\langle x+1, x^2 \rangle}{||x+1|| ||x^2||} = \frac{\sqrt{15}}{6}$   
The angle is  
 $\sqrt{15}$ 

$$\theta = \arccos(\frac{\sqrt{15}}{6})$$

# Question 10. (15 pts)

Let  $V = \operatorname{span}(e^x, e^{-x}, xe^x, xe^{-x})$  be a subspace of  $C^{\infty}$ . We know that V is a vector space with a basis

 $e^x, e^{-x}, xe^x, xe^{-x}.$ 

Let us denote this basis by  $\mathfrak{B}$ . Let

$$T(f) = 2f - f'$$

be a linear transformation from V to V .

(a) Find the matrix representation of T with the basis  $\mathfrak{B}$ .

Solution: The matrix is

$$A = \begin{pmatrix} 1 & 0 & -1 & 0 \\ 0 & 3 & 0 & -1 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 3 \end{pmatrix}$$

(b) Is T nonsingular? Justify your answer.

Solution:	$\det(A) = 9 \neq 0$
So $T$ is nonsingular.	

### Question 11. (15 pts)

The eigenvalues and corresponding eigenvectors of the matrix  $A = \begin{bmatrix} 1 & 1 & 0 \\ 0 & 2 & 2 \\ 0 & 0 & 3 \end{bmatrix}$  are  $\lambda_1 = 1$  with  $v_1 = (1, 0, 0)^T$ ,  $\lambda_2 = 2$  with  $v_2 = (1, 1, 0)^T$  and  $\lambda_3 = 3$  with  $v_3 = (1, 2, 1)^T$ . (a) Find the general solution to the system

$$\frac{d\mathbf{x}}{dt} = A\mathbf{x}.$$

Solution: The general solution is  $\mathbf{x}(t) = c_1 e^t \begin{bmatrix} 1\\0\\0 \end{bmatrix} + c_2 e^{2t} \begin{bmatrix} 1\\1\\0 \end{bmatrix} + c_3 e^{3t} \begin{bmatrix} 1\\2\\1 \end{bmatrix}$ In other words,  $\begin{bmatrix} x_1(t)\\x_2(t)\\x_3(t) \end{bmatrix} = \begin{bmatrix} c_1 e^t + c_2 e^{2t} + c_3 e^{3t}\\c_2 e^{2t} + 2c_3 e^{3t}\\c_3 e^{3t} \end{bmatrix}$  (b) Find a specific solution  $\mathbf{x}(t)$  such that

$$\mathbf{x}(0) = \begin{bmatrix} x_1(0) \\ x_2(0) \\ x_3(0) \end{bmatrix} = \begin{bmatrix} 6 \\ 4 \\ 1 \end{bmatrix}$$

when t = 0.

## Solution:

$$\begin{bmatrix} x_1(0) \\ x_2(0) \\ x_3(0) \end{bmatrix} = \begin{bmatrix} c_1 + c_2 + c_3 \\ c_1 + 2c_3 \\ c_3 \end{bmatrix}$$

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Therefore, we need to solve for  $c_1, c_2$  and  $c_3$  of the following linear system

$$\begin{bmatrix} c_1 + c_2 + c_3 \\ c_1 + 2c_3 \\ c_3 \end{bmatrix} = \begin{bmatrix} 6 \\ 4 \\ 1 \end{bmatrix}$$

which has a unique solution  $c_1 = 3, c_2 = 2$  and  $c_3 = 1$ . So the solution satisfying the given initial condition is

$$\begin{bmatrix} x_1(t) \\ x_2(t) \\ x_3(t) \end{bmatrix} = \begin{bmatrix} 3e^t + 2e^{2t} + e^{3t} \\ 2e^{2t} + 2e^{3t} \\ e^{3t} \end{bmatrix}$$